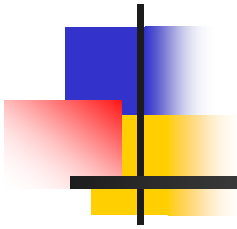


# Integration



Topic: Romberg Rule

Major: Computer Engineering

# Basis of Romberg Rule

## Integration

The process of measuring the area under a curve.

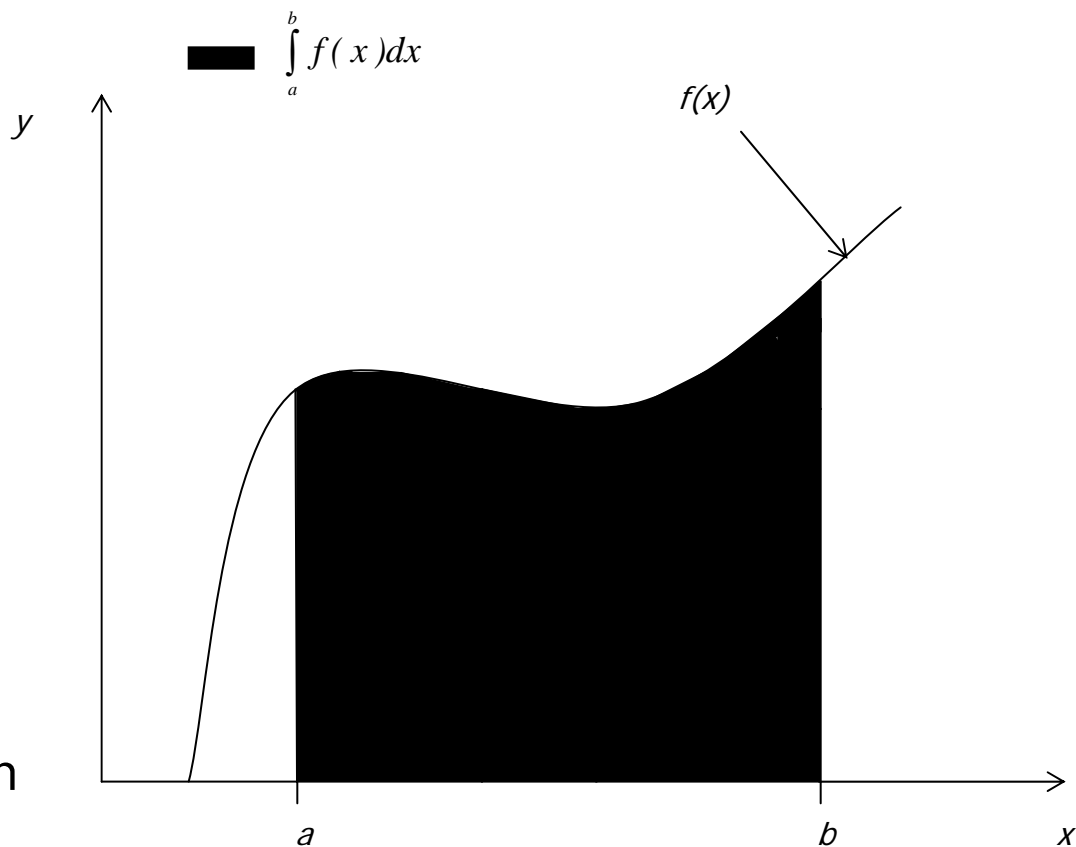
$$I = \int_a^b f(x) dx$$

Where:

$f(x)$  is the integrand

$a$  = lower limit of integration

$b$  = upper limit of integration





# What is The Romberg Rule?

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Romberg Integration is an extrapolation formula of the Trapezoidal Rule for integration. It provides a better approximation of the integral by reducing the True Error.



# Error in Multiple Segment Trapezoidal Rule

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The true error in a multiple segment Trapezoidal Rule with  $n$  segments for an integral

$$I = \int_a^b f(x) dx$$

Is given by

$$E_t = \frac{(b-a)^3}{12n^2} \frac{\sum_{i=1}^n f''(\xi_i)}{n}$$

where for each  $i$ ,  $\xi_i$  is a point somewhere in the domain,  $[a + (i-1)h, a + ih]$ .



# Error in Multiple Segment Trapezoidal Rule

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The term  $\frac{\sum_{i=1}^n f''(\xi_i)}{n}$  can be viewed as an approximate average value of  $f''(x)$  in  $[a, b]$ .

This leads us to say that the true error,  $E_t$  previously defined can be approximated as

$$E_t \cong \alpha \frac{1}{n^2}$$

# Error in Multiple Segment Trapezoidal Rule

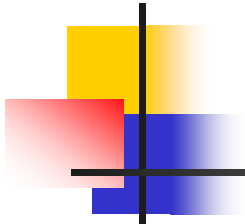


Table 1 shows the results obtained for the integral using multiple segment Trapezoidal rule for

$$\begin{aligned}
 f(x) &= 0, \quad 0 < x < 30 \\
 &= -9.1688 \times 10^{-6} x^3 + 2.7961 \times 10^{-3} x^2 - \\
 &\quad 2.8487 \times 10^{-1} x + 9.6778, \quad 30 \leq x \leq 172 \\
 &= 0, \quad 172 < x < 200
 \end{aligned}$$

n	Value	$E_t$	$ \epsilon_t \%$	$ \epsilon_a \%$
1	-0.85	61.6426	101.398	---
2	63.4975	-2.7049	4.44939	101.338
3	111.257	-50.4648	83.0114	42.927
4	36.061	24.73073	40.68049	208.518
5	58.427	2.36519	3.8906	38.279
6	77.769	-16.9765	27.9253	24.870
7	42.527	18.2648	30.0444	82.866
8	55.753	5.03879	8.2885	23.722

Table 1: Multiple Segment Trapezoidal Rule Values



# Error in Multiple Segment Trapezoidal Rule

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The true error gets approximately quartered as the number of segments is doubled. This information is used to get a better approximation of the integral, and is the basis of Richardson's extrapolation.



# Richardson's Extrapolation for Trapezoidal Rule

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The true error,  $E_t$  in the  $n$ -segment Trapezoidal rule is estimated as

$$E_t \cong \frac{C}{n^2}$$

where  $C$  is an *approximate constant* of proportionality. Since

$$E_t = TV - I_n$$

Where TV = true value and  $I_n$  = approx. value



# Richardson's Extrapolation for Trapezoidal Rule

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From the previous development, it can be shown that

$$\frac{C}{(2n)^2} \cong TV - I_{2n}$$

when the segment size is doubled and that

$$TV \cong I_{2n} + \frac{I_{2n} - I_n}{3}$$

which is Richardson's Extrapolation.



# Example 1

Human vision has the remarkable ability to infer 3D shapes from 2D images. The intriguing question is: can we replicate some of these abilities on a computer? Yes, it can be done and to do this, integration of vector fields is required. The following integral needs to be integrated.

$$I = \int_0^{100} f(x) dx$$

where

$$f(x) = 0, \quad 0 < x < 30$$

$$= -9.1688 \times 10^{-6} x^3 + 2.7961 \times 10^{-3} x^2 - 2.8487 \times 10^{-1} x + 9.6778,$$

$$30 \leq x \leq 172$$

$$= 0, \quad 172 < x < 200$$

- a) Use Richardson's rule to find the distance covered. Use the 2-segment and 4-segment Trapezoidal rule results given in Table 1.
- b) Find the true error,  $E_t$  for part (a).
- c) Find the absolute relative true error,  $|\varepsilon_a|$  for part (a).



# Solution

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a)  $I_2 = 63.4975$        $I_4 = 36.061$

Using Richardson's extrapolation formula  
for Trapezoidal rule

$$TV \cong I_{2n} + \frac{I_{2n} - I_n}{3} \quad \text{and choosing } n=2,$$

$$\begin{aligned} TV &\cong I_4 + \frac{I_4 - I_2}{3} = 63.4975 + \frac{63.4975 - 36.061}{3} \\ &= 72.643 \end{aligned}$$



## Solution (cont.)

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- b) The exact value of the above integral is found using Maple for calculating the true error and relative true error.

$$\begin{aligned} I &= \int_0^{100} f(x) dx \\ &= 60.7926 \end{aligned}$$

Hence

$$\begin{aligned} E_t &= \textit{True Value} - \textit{Approximate Value} \\ &= 60.7926 - 72.643 \\ &= -11.8504 \end{aligned}$$



## Solution (cont.)

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c) The absolute relative true error  $|\epsilon_t|$  would then be

$$|\epsilon_t| = \left| \frac{60.7926 - 72.643}{60.7926} \right| \times 100$$
$$= 19.49\%$$

Table 2 shows the Richardson's extrapolation results using 1, 2, 4, 8 segments. Results are compared with those of Trapezoidal rule.



# Solution (cont.)

Table 2: The values obtained using Richardson's extrapolation formula for Trapezoidal rule for

$$f(x) = 0, \quad 0 < x < 30$$

$$= -9.1688 \times 10^{-6} x^3 + 2.7961 \times 10^{-3} x^2 - 2.8487 \times 10^{-1} x + 9.6778, \quad 30 \leq x \leq 172$$

$$= 0, \quad 172 < x < 200$$

n	Trapezoidal Rule	$ \epsilon_r $ for Trapezoidal Rule	Richardson's Extrapolation	$ \epsilon_r $ for Richardson's Extrapolation
1	-0.85	101.398	--	--
2	63.4975	4.44939	84.947	39.732
4	36.061	40.68049	72.643	19.49
8	55.753	8.2885	62.317	2.508

**Table 2: Richardson's Extrapolation Values**



# Romberg Integration

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Romberg integration is same as Richardson's extrapolation formula as given previously. However, Romberg used a recursive algorithm for the extrapolation. Recall

$$TV \cong I_{2n} + \frac{I_{2n} - I_n}{3}$$

This can alternately be written as

$$(I_{2n})_R = I_{2n} + \frac{I_{2n} - I_n}{3} = I_{2n} + \frac{I_{2n} - I_n}{4^{2-1} - 1}$$



# Romberg Integration

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Note that the variable  $TV$  is replaced by  $(I_{2n})_R$  as the value obtained using Richardson's extrapolation formula. Note also that the sign  $\cong$  is replaced by  $=$  sign. Hence the estimate of the true value now is

$$TV \cong (I_{2n})_R + Ch^4$$

Where  $Ch^4$  is an approximation of the true error.



# Romberg Integration

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Determine another integral value with further halving the step size (doubling the number of segments),

$$(I_{4n})_R = I_{4n} + \frac{I_{4n} - I_{2n}}{3}$$

It follows from the two previous expressions that the true value TV can be written as

$$\begin{aligned} TV &\cong (I_{4n})_R + \frac{(I_{4n})_R - (I_{2n})_R}{15} \\ &= I_{4n} + \frac{(I_{4n})_R - (I_{2n})_R}{4^{3-1} - 1} \end{aligned}$$



# Romberg Integration

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A general expression for Romberg integration can be written as

$$I_{k,j} = I_{k-1,j+1} + \frac{I_{k-1,j+1} - I_{k-1,j}}{4^{k-1} - 1}, k \geq 2$$

The index  $k$  represents the order of extrapolation.  $k=1$  represents the values obtained from the regular Trapezoidal rule,  $k=2$  represents values obtained using the true estimate as  $O(h^2)$ . The index  $j$  represents the more and less accurate estimate of the integral.



## Example 2

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Human vision has the remarkable ability to infer 3D shapes from 2D images. The intriguing question is: can we replicate some of these abilities on a computer? Yes, it can be done and to do this, integration of vector fields is required. The following integral needs to be integrated.

$$I = \int_0^{100} f(x) dx$$

where

$$f(x) = 0, \quad 0 < x < 30$$

$$= -9.1688 \times 10^{-6} x^3 + 2.7961 \times 10^{-3} x^2 - 2.8487 \times 10^{-1} x + 9.6778,$$

$$30 \leq x \leq 172$$

$$= 0, \quad 172 < x < 200$$

Use Romberg's rule to find the distance covered. Use the 1, 2, 4, and 8-segment Trapezoidal rule results as given in the Table 1.



# Solution

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From Table 1, the needed values from original Trapezoidal rule are

$$I_{1,1} = -0.85$$

$$I_{1,2} = 63.4975$$

$$I_{1,3} = 36.061$$

$$I_{1,4} = 55.753$$

where the above four values correspond to using 1, 2, 4 and 8 segment Trapezoidal rule, respectively.



## Solution (cont.)

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To get the first order extrapolation values,

$$\begin{aligned} I_{2,1} &= I_{1,2} + \frac{I_{1,2} - I_{1,1}}{3} \\ &= 63.4975 + \frac{63.4975 - (-0.85)}{3} \\ &= 84.947 \end{aligned}$$

Similarly,

$$\begin{aligned} I_{2,2} &= I_{1,3} + \frac{I_{1,3} - I_{1,2}}{3} \\ &= 36.061 + \frac{36.061 - 63.4975}{3} \\ &= 26.917 \end{aligned}$$

$$\begin{aligned} I_{2,3} &= I_{1,4} + \frac{I_{1,4} - I_{1,3}}{3} \\ &= 55.753 + \frac{55.753 - 36.061}{3} \\ &= 62.318 \end{aligned}$$



## Solution (cont.)

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For the second order extrapolation values,

$$\begin{aligned}I_{3,1} &= I_{2,2} + \frac{I_{2,2} - I_{2,1}}{15} \\ &= 26.917 + \frac{26.917 - 84.947}{15} \\ &= 23.048\end{aligned}$$

Similarly,

$$\begin{aligned}I_{3,2} &= I_{2,3} + \frac{I_{2,3} - I_{2,2}}{15} \\ &= 62.318 + \frac{62.318 - 26.917}{15} \\ &= 64.678\end{aligned}$$



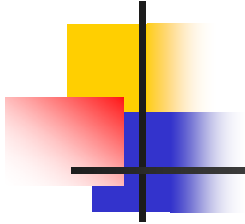
## Solution (cont.)

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For the third order extrapolation values,

$$\begin{aligned} I_{4,1} &= I_{3,2} + \frac{I_{3,2} - I_{3,1}}{63} \\ &= 64.678 + \frac{64.678 - 23.048}{63} \\ &= 65.338 \end{aligned}$$

Table 3 shows these increased correct values in a tree graph.



# Solution (cont.)

**Table 3: Improved estimates of the integral value using Romberg Integration**

		1 <sup>st</sup> Order	2 <sup>nd</sup> Order	3 <sup>rd</sup> Order
1-segment	-0.85			
		84.947		
2-segment	63.4975		23.048	
		26.917		65.338
4-segment	36.061		64.678	
		62.318		
8-segment	55.753			